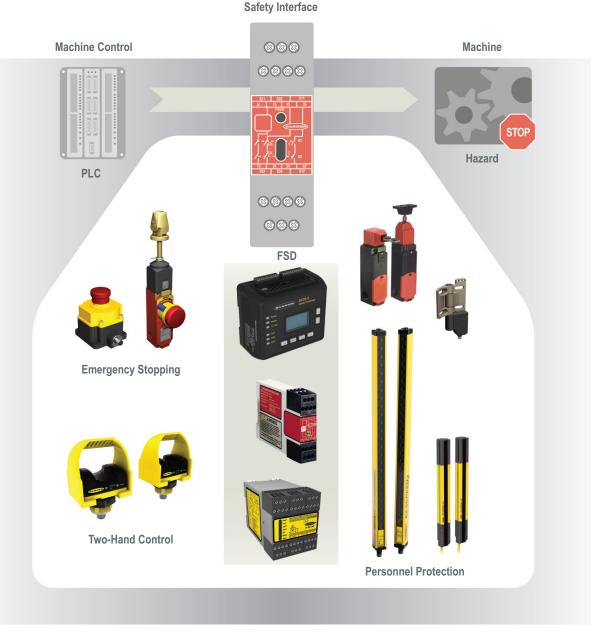
Safeguarding Basics





Basics of Safeguarding

Machine and personnel safeguarding refers to the combination of requirements, methods and solutions used to protect people who come in contact with dangerous machines in the industrial environment.

Requirements

National and regional governmental bodies have regulations, mandates, standards and recommendations for implementing a safety method or a solution.

Key regulations regarding general machine guarding include the following:

- Machinery Directive EU
- OSHA General Duty Clause USA

(see page 512 for an abridged version list of industry safety standards)

Device Requirements

Safety devices must be able to consistently and reliably bring a machine hazard to an orderly stop.

To be considered a safety device, the following methods must be used to ensure reliable operation: fault exclusion, redundancy and self-checking.

Safety Circuit Requirements

A safety stop circuit typically comprises of 2 normally-open contact from mechanically-linked relays. The circuit is monitored to detect certain failures that could lead to the loss of the safety function.

Methods: Risk Assessment

The Risk Assessment Process in machine safeguarding is a process used to identify hazards through each phase of the machine's life cycle and to minimize dangers to personnel and equipment.

The basic steps in a Risk Assessment Process:

- 1. Identify hazards and where they occur.
- 2. Assess risk by severity of harm and probability of occurrence.
- 3. Reduce the risk through the use of protective measures.
- 4. Validate and document results.

Risk Assessment Standards

- OSHA 3071, Job Hazard Analysis
- MIL-STD-8820, US DOD System Safety Program
- ANSI B11.0 General (Safety) Requirements and Risk Assessment
- · ISO 12100, General Principles for Design, Risk Assessment and Risk Reduction
- SEMI S10, Risk Assessment, Semiconductor Manufacturing Equipment

Methods: Safety Circuits

Depending on the level of risk associated with the machine or operations, an appropriate level of control circuitry performance must be incorporated into safety device design.

	Basic	Single	Single with Monitoring	Dual with Monitoring		
	Stop Command	Protective Command	Protective Command Monitoring Signal	Redundant (Safety) Stop Commands Monitoring Signal		
Generic	Simple Device	Safe- Guarding Device	Safe- Guarding Device	Safe- Guarding Device		
	 Non safety-rated components Integrated in accordance with relevant standards Reliability depends on robust components Redundancy not required 	 Safety-rated components Integrated in accordance with safety principles and design Redundancy not required 	 Safety-rated components Conducts periodic test of system Normal operation allowed if no faults are found If unsafe fault is found, system will default to safe state or indicate that unsafe system exists 	 Safety-rated components Greatest degree of fault tolerance Redundancy and self-checking Single failure cannot cause loss of safety function Faults detected immediately or at next demand on system 		
Fault	Possible loss of safety function	Possible loss of safety function Greater reliability, but possible loss of safety function Fault detected at each te		Safety function is ensured with a single fault. An accumulation of faults is not possible or detected.		
Risk	Very Low Minor bump or bruise with no lost time	Low Minor first aid, infrequent exposure or high likelihood of avoiding the hazard	Mid Range Injuries that are slight or normally reversible, requiring normal healing or only first aid	High or Very High Normally reserved for hand-fed applications where injuries could be severe to irreversible		
ANSI / B11	_	_	_	Control Reliable ANSI B11.19 (Clause 6.1 and Annex C) Category 3 or 4 and/or PL d or PL e per ISO 13849-1 satisfy Control Reliability requirements		
ANSI / RIA	Simple	Simple Single Channel		Control Reliable ANSI/RIA R15.06 (1999 Clause 4.5) Control reliability for robots typically exceeds a Cat 3 but is not necessarily intended to be a Cat 4		
ISO / EN	Category B ISO 13849-1/EN 954-1	Category 1 ISO 13849-1/EN 954-1	Category 2 ISO 13849-1/EN 954-1	Category 3 & 4 ISO 13849-1/EN 954-1		

Photoelectrics Sensors Fiber Optic Sensors

Measurement & Inspection Sensors

Special Purpose Sensors

Vision

Lighting & Indicators

Wireless Safety Light Screens Safety Laser Scanners Safety Controllers & Modules Safety Two-Hand Control Modules

Safety Interlock Switches

Emergency Stop & Stop Control

Solutions: Comparing Guards and Devices*

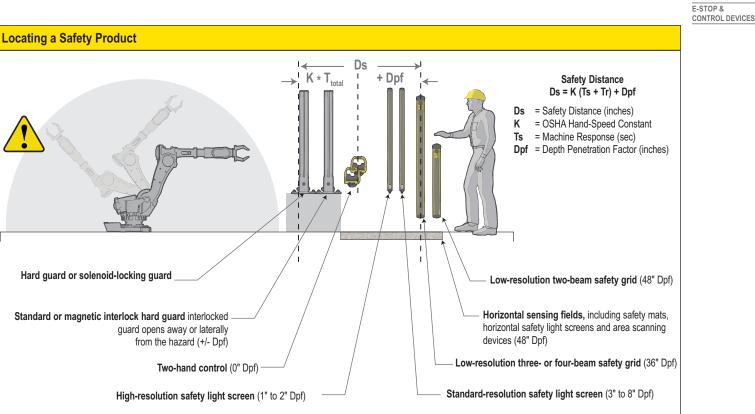
Туре	Safety Function	Advantages	Limitations	Requirements	Standards
		Guards: protective physic	al barrier used to prevent access	5.	
Fixed Guard	Provides a fixed barrier to the hazard	Low maintenance Long life Low cost for small areas Protects all individuals Can contain ejected materials	Poor ergonomics Limited visibility Limited access Costly for large areas Maintenance may require removal of guard	 Protect from identified hazard Prevent user from reaching over, under, around or through the barrier Provide safe openings 	• ANSI B11.19 • ISO 14120 • ISO 13857
Interlocked Guard	Interrupts power to machine when guard is opened	 Low initial investment Can be placed close to hazard Protects all individuals Can contain ejected materials 	Costly for large areas Increased maintenance	 Must be difficult to defeat Guard may open only after machine has stopped-or must be installed at a safe distance 	• ANSI B11.19 • NFPA 79 • ISO 14119 • ISO 14120 • IEC 60204-1 • ISO 13857 • ISO 13855
;	Safeguarding Devices: co	mponents, attachments or me	chanisms designed to perform a	specific safeguarding function	ı.
Safety Light Screen	Arrests power to machine when sensing field is interrupted	Excellent ergonomics Allows frequent access Protects all individuals Cost effective for large areas Allows for good visibility	 Limited to machines that can be stopped quickly No protection from ejected parts May require the use of additional guards May create a pass-through hazard 	 Initiate immediate stop when sensing field is interrupted Appropriate resolution required to detect objects the size of a torso, ankle, hand or finger 	• ANSI B11.19 • IEC 61496 • ISO 13855
Multiple-Beam System: • Grids • Points	Arrests power to machine when sensing field is interrupted	Low initial investment Allows frequent access Allows for good visibility Protects all individuals	 Limited to machines that can be stopped quickly No protection from ejected parts Large safety distance May create a pass-through hazard 	 Initiate immediate stop when sensing field is interrupted Appropriate resolution required to detect objects the size of a torso 	• ANSI B11.19 • IEC 61496 • ISO 13855
Two-Hand Control	Operator must use both hands to actuate machine motion hereby preventing operator access to hazardous area	 Operator's hands are away from hazardous area Low initial investment Low maintenance 	Potential ergonomic impact Provides protection only for operator No protection from ejected parts	 Concurrent actuation within 1/2 second Release and reactivation required before machine motion may be reinitiated 	ANSI B11.19 NFPA 79 ISO 13851 IEC 60204-1 ISO 13855
Safety Mat Monitor			Costly for large areas Maintenance intensive Large safety distance	Minimum object sensitivity of 66 lbs on and 3-1/8" surface to detect a foot	• ANSI B11.19 • ISO 13855 • ISO 13856
	Co	mplementary Safety Devices:	used to supplement a primary sa	feguard.	
E-Stop • Button • Rope Pull	ton in emergency situation to • Safe shutdown of machin		Not considered a safeguard Requires conscious act of operator Limits injury or machine damage but typically does not prevent it	 Overrides all other functions and operations Reset of E-stop doesn't initiate machine motion Button must be red with yellow background Should be located at each operation station Final removal of power done by electromechanical components 	ANSI B11.19 NFPA 79 ISO 12100 IEC 60204-1 ISO 13850

*This represents a partial list of available safeguards & devices.

Solutions: Choosing and Locating a Safeguard

When choosing a safeguard, ask yourself the following questions: 1) is it safe, 2) is it legal and 3) does it make sense for the application.

Choosing a Safety Produ	ct											Special Purpose Sensors
 Who will use it? How will they use it? What hazards are associated with which task? What are the types of hazards? Where will the coferenced be 	E = Excellent A = Acceptable P = Poor X = Not Acceptable Guarding Solutions	Maintenance \$	Frequent Access	Infrequent Access	Locate Close to Hazard	Long Machine Stop Time	Ergonomic	Visibility	Multiple Operators	Guards Against Ejected Material	Comments	Vision Lighting & Indicators Wireless Safety Light Screens Safety Laser Scanners
Where will the safeguard be located?	Fixed Hard Guard	Р	Р	Е	Е	Е	Р	Р	Е	Е	 Limited access Limited visibility to the machine Costly for large areas Costly to maintain and fix 	Safety Controllers & Modules
	Locking Guard	Р	Р	Е	E	E	Р	Р	Е	E		Safety Two-Hand Control Modules
												Safety Interlock Switches
	Interlock Guard	Р	P	A	E	A	Р	P	E	E		Emergency Stop & Stop Control
	Two-Hand Control	A	A	A	A	A	Α	A	Р	Р	Only protects operator(s)	
	High-Resolution SLS	Е	E	Р	Е	Р	Е	E	E	Х	Locate closer to hazard	
	Low-Resolution SLS	Е	E	Р	Е	Р	E	E	E	Х	Costs less than high resolution SLS	_
	3- or 4-Beam Perimeter	Е	A	A	Р	A	Е	Е	Е	Х	Takes less space than 2-beam	LIGHT SCREENS
	2-Beam Perimeter	E	A	A	Р	A	E	E	E	X	Costs less than 3- or 4-beam	LASER SCANNER CONTROLLERS & MODULES
	Safety Mats	Р	A	A	Р	A	E	E	Е	Х	Maintenance-intensive	TWO-HAND CONTROL MODULES INTERLOCK
	1										4	SWITCHES



NOTE: Illustration examples are based upon the described safeguards being used as the primary safeguarding device, all examples having identical stopping time, and following generally accepted industrial engineering practices that are found within ANSI B11.19 safety standard. Photoelectrics Sensors Fiber Optic Sensors

Measurement & Inspection Sensors

Requirements: Standards

Safety and Safeguarding standards are minimum requirements for product and machine design, manufacture, use and evaluation that guide the methods used to improve safety. Note: The following is not all inclusive and is provided for information only. Superseded designations are contained in parentheses.

<u>General Requirements (A & B standards)</u> U.S.

OSHA 29CFR1910.212 General Requirements for All Machines OSHA 3071 Job Hazard Analysis ANSI B11.0 (ANSI B11.TR3) General Requirements and Risk Assessment OSHA 29 CFR 1910.147 The Control of Hazardous Energy (lockout/ tagout) ANSI Z244.1 Lockout/Tagout of Energy Sources ANSI/NFPA 79

Electrical Standard for Industrial Machinery

International/European ISO 12100 (ISO 12100-1/-2 and ISO 14121) General Principles for Design - Risk Assessment and

Risk Reduction ISO 14118 (EN 1037) Prevention of Unexpected Start Up IEC 60204-1 Electrical Equipment of Machines: General Requirements

Safety and Safeguarding Design

U.S. ANSI B11.19 Performance Criteria for Safeguarding ANSI B11.20 Integrated Manufacturing Systems ANSI B11.24 Transfer Machines ANSI B11.TR1 Ergonomic Guidelines ANSI B11.TR5 Sound Level Measurement Guidelines ANSI B11.TR6 Safety Control Systems ANSI Z535 series Safety Signs, Tags/Labels, Symbols, Color Codes and Manuals/Instructions

International/European ISO 11161 Integrated Manufacturing Systems ISO 14119 (EN 1088) Interlocking Devices Associated with Guards ISO 14120 (EN 953) Guards

ISO 13849-1 (EN 954-1) Safety Related Parts of Control Systems ISO 13850 (EN 418) Emergency Stop Devices ISO 13851 (EN 574) Two-Hand Control Devices ISO 13854 (EN 349) Minimum gaps to avoid crushing of parts of the human body ISO 13855 (EN 999) The Positioning of Protective Equipment ISO 13857 (ISO 13852/EN 294, ISO 13853/EN 811) Safety Distances [openings] - Upper and Lower Limbs IEC 61508 Functional Safety of electrical/electronic/programmable electronic safety-related systems ISO 62061 Functional Safety of Safety-Related Electrical, Electronic and Programmable Control Systems

Machine Specific Applications, Grouped by Type (C Standards) Mechanical Power Transmission Apparatus OSHA 29CFR1910.219 Nate: ANSI/ASME R15.1 Mechanical Power Trans

Note: ANSI/ASME B15.1 Mechanical Power Transmission Apparatus has been incorporated into ANSI B11.0 & ANSI B11.19.

Machine Tools- Mechanical Power Presses (Note: Refer to the ANSI B11.xx series for additional Machine Tool standards) OSHA 29CFR1910.217 ANSI B11.1 EN 692

Conveyors ANSI/ASME B20.1 ISO 9851

Industrial Robots

ANSI/RIA R15.06 ISO 10218 (EN 775)

Injection Molding / Extruding (Rubber & Plastics)

ANSI B151.xx series EN 201 EN 1114-1 EN289 EN422 EN1612

Mills and Calenders OSHA 29CFR1910.261

OSHA 29CFR1910.216 ANSI B28.1 EN 1417

Packaging ANSI/PMMI B155.1 EN 415 series

Semiconductor SEMI Sxx series

SEMI SXX series SEMI S2 SEMI S10

Lasers ANSI Z136.1 ANSI B11.21

Turning Machines / Machining Centers ANSI B11.22 ANSI B11.23

These and other standards are available from: OSHA Documents: http://www.osha.gov American National Standards Institute (ANSI): http://www.ansi.org NSSN National Resource for Global Standards: http://www.nssn.org/

Safety Standards Acronyms

- ANSI: American National Standards Institute
- CE: Mark of European Conformity
- **CEN:** European Committee for Standardization
- CENELEC: European Committee for Electrotechnical Standardization
- CSA: Canadian Standards Association
- EN: European Norm
- IEC: International Electrotechnical Commission
- ISO: International Organization for Standardization
- OSHA: Occupation Safety and Health Administration
- SEMI: Semiconductor Equipment and Materials International
- UL: Underwriters Laboratory